

Cantilever axes EGSA, with spindle drive



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Key features

At a glance

The spindle driven cantilever axis EGSA reduces cycle times to an absolute minimum. This is thanks to a powerful mechanical system and a range of motor choices adapted to the requirements of the application.

In contrast to the electric cantilever axis DGEA designed for longer strokes, the EGSA demonstrates its strengths with short strokes.

Advantages:

- Maximum precision
- High dynamic response
- Repetition accuracy of ± 0.01 mm

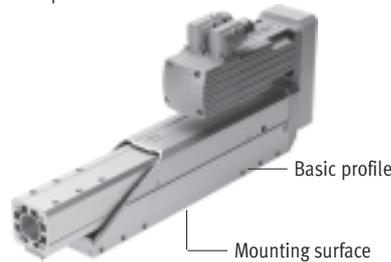
Complete system comprises cantilever axis, motor, motor controller and motor mounting kit

Spindle driven cantilever axis

With axial kit



With parallel kit



 Note

The spindle driven cantilever axis must only be mounted using the underside of the base profile (→ picture on left). The lateral holes on the base profile are provided for securing accessories (e.g. protective trunking).

Motor

→ 11



- 1 Servo motor EMMS-AS
- 2 Stepper motor EMMS-ST

 Note

A range of specially adapted complete solutions is available for the spindle driven cantilever axis EGSA and the motors.

Motor controller

Technical data → Internet: motor controller



- 1 Servo motor controller CMMP-AS
- 2 Stepper motor controller CMMS-ST

Motor mounting kit

→ 11

Axial kit



Parallel kit



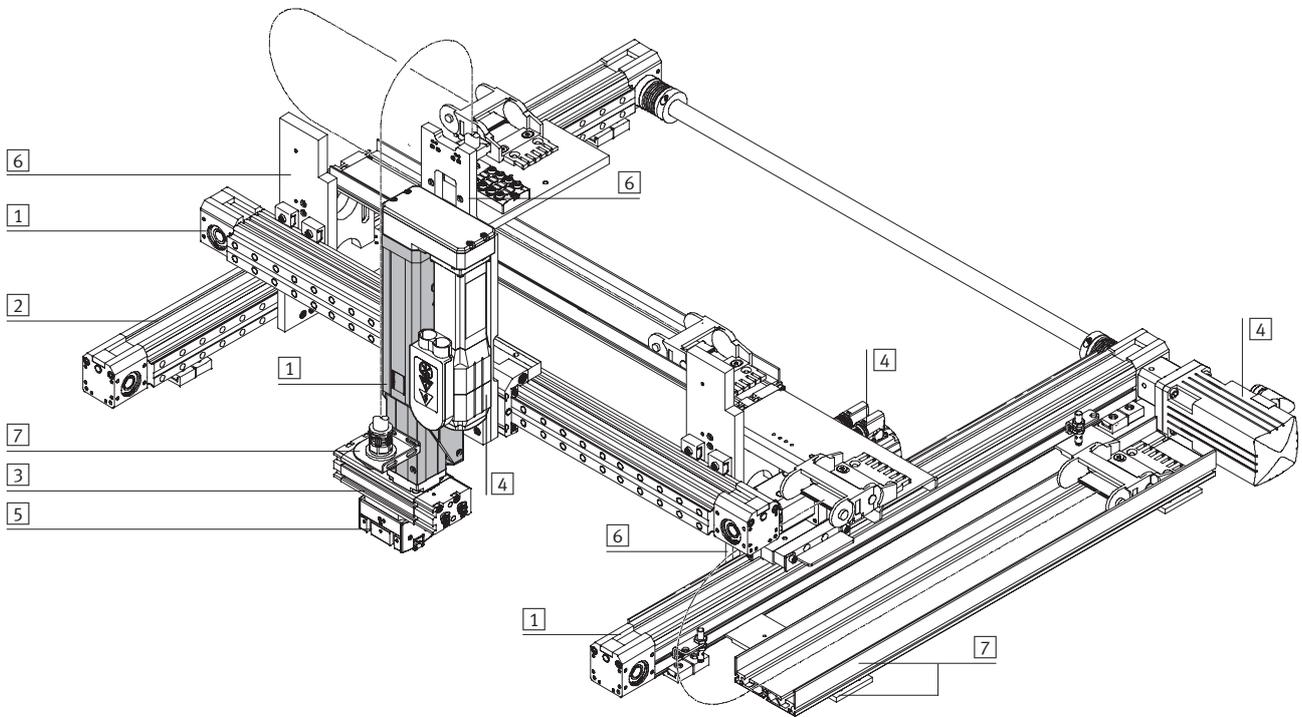
There are complete kits for both parallel and axial motor mounting.

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Key features

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System product for handling and assembly technology



System components and accessories		
	Brief description	→ Page/Internet
1	Axes	Wide range of combinations possible within handling and assembly technology axes
2	Guide axes	To increase force and torque capacity in multi-axis applications guide axes
3	Drives	Wide range of combinations possible within handling and assembly technology drive
4	Motors	Servo and stepper motors motor
5	Grippers	Wide range of variations possible within handling and assembly technology gripper
6	Adapters	For drive/drive and drive/gripper connections adapter kit
7	Installation components	For a clean, safe layout of electrical cables and tubing installation component

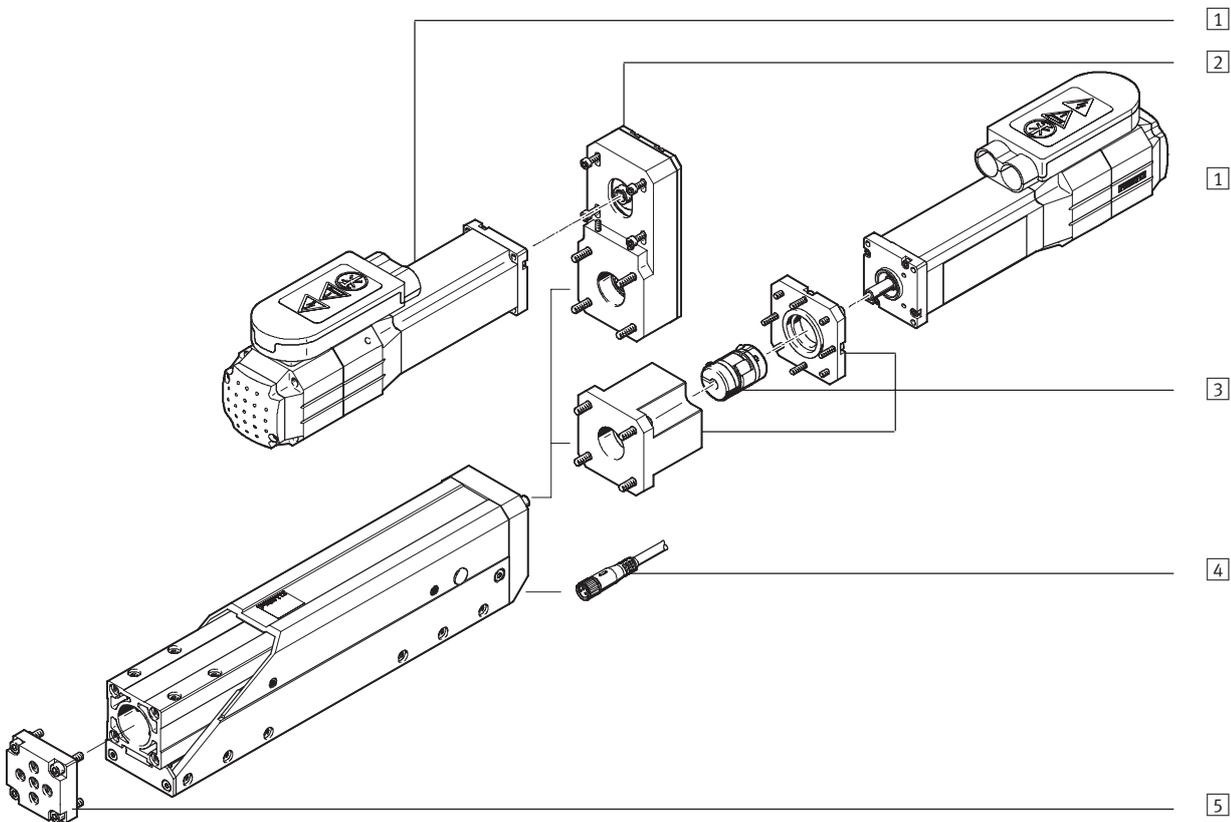
Cantilever axes EGSA, with spindle drive

Type codes and peripherals overview

Type codes

EGSA		50	100
Type			
EGSA	Cantilever axis with spindle drive		
Size			
Stroke [mm]			

Peripherals overview



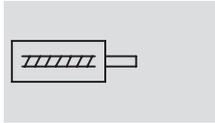
Accessories			
Type	Brief description		→ Page/Internet
1 Motor EMMS	<ul style="list-style-type: none"> • Motors specially matched to the axis, with or without brake • The motor can be turned by 90° for mounting, depending on requirements. This means the connection side can be freely selected 		11
2 Parallel kit EAMM-U	For parallel motor mounting (consisting of: housing, clamping component, clamping sleeve, toothed belt pulley, toothed belt)		11
3 Axial kit EAMM-A	For axial motor mounting (consisting of: coupling, coupling housing and motor flange)		11
4 Connecting cable NEBU	For connecting the proximity sensor to a controller. The proximity sensor (N/C contact) is integrated in the spindle driven cantilever axis		14
5 Adapter kit HMSV	Interface between the spindle driven cantilever axis and drive or gripper		14

Cantilever axes EGSA, with spindle drive

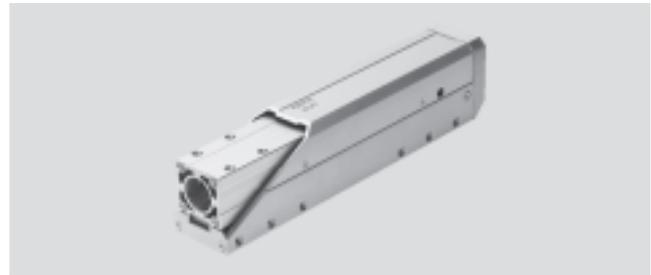
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Technical data

Function



-  - Size
50 and 60
-  - Stroke length
100 ... 300 mm



General technical data					
Size	50		60		
Constructional design	Electromechanical cantilever axis with recirculating ball bearing spindle and roller bearing guide				
Working stroke	[mm]	100	100	200	300
Stroke reserve	[mm]	-3/+7	-4/+9		
Max. speed	[m/s]	1.0	1.5		1.0
Max. rotational speed	[rpm]	3,000			
Max. acceleration ¹⁾	[m/s ²]	15			
Reversing backlash ²⁾	[mm]	≤ 0.02			
Repetition accuracy	[mm]	±0.01			
Position sensing	Sensing of the reference point via integrated reference sensor (N/C contact)				
Type of mounting	Via female thread and centring sleeve				
Mounting position	Any				

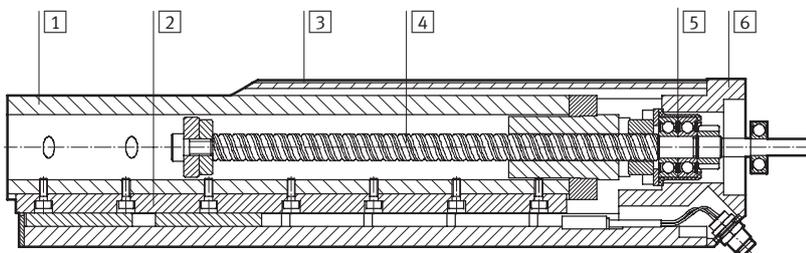
- 1) At max. effective load
- 2) In new condition

Operating and environmental conditions				
Size	50		60	
Ambient temperature ¹⁾	[°C]	0 ... 50		
Storage temperature	[°C]	0 ... 50		
Duty cycle	[%]	100		
Noise level	[dB]	< 58	< 62	
Protection class	IP20			
Relative air humidity ²⁾	[%]	0 ... 95		

- 1) Note operating range of proximity sensors and motors
- 2) Non-condensing

Materials

Sectional view



Spindle driven cantilever axis		
1	Cantilever profile	Wrought aluminium alloy, anodised
2	Guide rail	Rolled steel
3	Housing profile, cover	Wrought aluminium alloy, anodised
4	Ball screw	Steel
5	Ball bearing	Steel
6	Spindle bearing plate	Wrought aluminium alloy, anodised
-	Note on material	Conforms to RoHS

Cantilever axes EGSA, with spindle drive

Technical data



Weight					
Size		50	60		
Stroke	[mm]	100	100	200	300
Basic weight	[g]	2,000	3,300	4,200	5,100
Moving load	[g]	750	1,350	1,800	2,250

Mass moment of inertia					
Size		50	60		
Stroke	[mm]	100	100	200	300
Total	[kgmm ²]	2	21.9	29.8	37.8
Per kg of effective load	[kgmm ² /kg]	2.5	16.4		

Mechanical data					
Size		50	60		
Spindle diameter	[mm]	10	12.7		
Spindle pitch	[mm/rev.]	10	25.4		
Max. feed force $F_{xmax.}$	[N]	120	240		
Continuous feed force	[N]	100	200		
Max. effective load, horizontal	[kg]	5	10		
Max. effective load, vertical	[kg]	3	6		
Continuous driving torque	[Nm]	0.2	1		
Max. radial force ¹⁾	[N]	60	110		

1) On the drive shaft

Calculation of the mean feed force F_{xm}

The peak feed force value must not exceed the maximum feed force within a movement cycle. In the case of vertical operation, the peak value is generally

achieved during the acceleration phase of the upwards stroke. If the maximum feed force is exceeded, this can increase wear and thus shorten

the service life of the ball screw spindle. The maximum speed must likewise not be exceeded.

$$F_x \leq F_{xmax.}$$

and

$$v_x \leq v_{xmax.}$$

Mean feed force (to DIN 69 051-4)

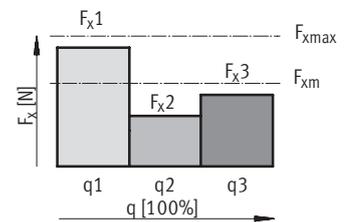
During operation, the continuous feed force may be briefly exceeded up to the maximum feed force. The continu-

ous feed force must, however, be adhered to when averaged over a movement cycle.

$$F_{xm} \leq F_{xcont}$$

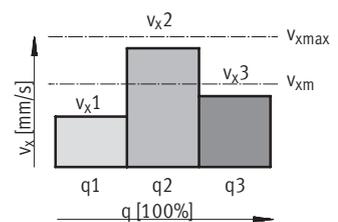
$$F_{xm} = \sqrt[3]{\sum F_x^3 \times \frac{v_x}{v_{xm}} \times \frac{q}{100}} =$$

$$F_{xm} = \sqrt[3]{F_{x1}^3 \times \frac{v_{x1}}{v_{xm}} \times \frac{q_1}{100} + F_{x2}^3 \times \frac{v_{x2}}{v_{xm}} \times \frac{q_2}{100} + F_{x3}^3 \times \frac{v_{x3}}{v_{xm}} \times \frac{q_3}{100} + \dots}$$



Mean feed speed (to DIN 69 051-4)

$$v_{xm} = \sum v_x \times \frac{q}{100} = v_{x1} \times \frac{q_1}{100} + v_{x2} \times \frac{q_2}{100} + v_{x3} \times \frac{q_3}{100} + \dots$$



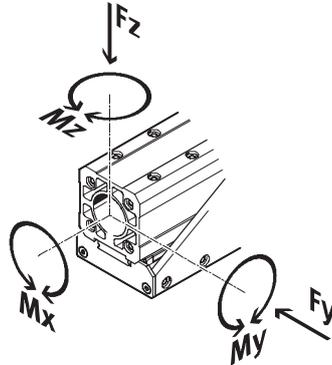
F_x	Feed force	v_x	Feed speed
F_{xm}	Mean feed force	v_{xm}	Mean feed speed
$F_{xmax.}$	Max. feed force	$v_{xmax.}$	Max. feed speed
F_{xcont}	Continuous feed force		
q	Time		

Cantilever axes EGSA, with spindle drive

Technical data

Characteristic load values of the guide

The indicated forces and torques refer to the centre of the guide rail. They must not be exceeded during dynamic operation. Special attention must be paid to the cushioning phase.



If the cantilever axis is simultaneously subjected to several of the forces and torques listed below, the following equation must be satisfied in addition to the indicated maximum loads:

$$\left| \frac{F_y}{F_{y_{max.}}} \right| + \left| \frac{F_z}{F_{z_{max.}}} \right| + \left| \frac{M_x}{M_{x_{max.}}} \right| + \left| \frac{M_y}{M_{y_{max.}}} \right| + \left| \frac{M_z}{M_{z_{max.}}} \right| \leq 1$$

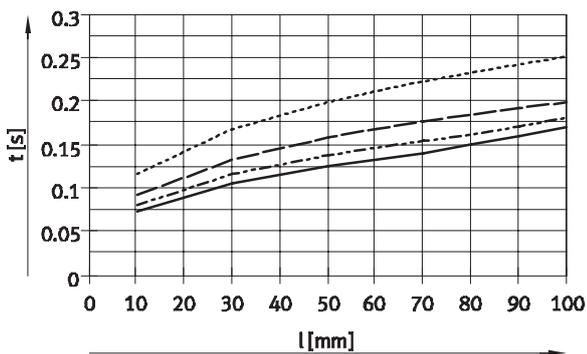
Permissible forces and torques

Size		50	60
F _{y_{max.}}	[N]	150	200
F _{z_{max.}}	[N]	150	200
M _{x_{max.}}	[Nm]	10	25
M _{y_{max.}}	[Nm]	25	70
M _{z_{max.}}	[Nm]	25	70

 Note
Sizing software
PositioningDrives
→www.festo.com

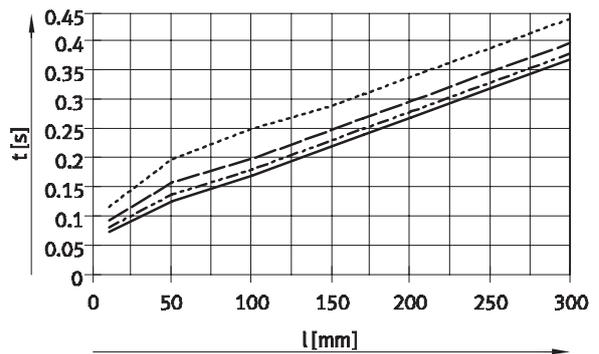
Positioning time t as a function of working stroke l and load m

EGSA-50-100 with servo motor EMMS-AS-40...



— m = 0 kg
- - - m = 1 kg
- · - m = 2 kg
- · · - m = 3 kg

EGSA-60-300 with servo motor EMMS-AS-55...

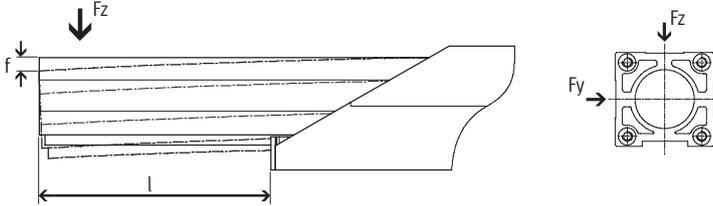


— m = 0 kg
- - - m = 2 kg
- · - m = 4 kg
- · · - m = 6 kg

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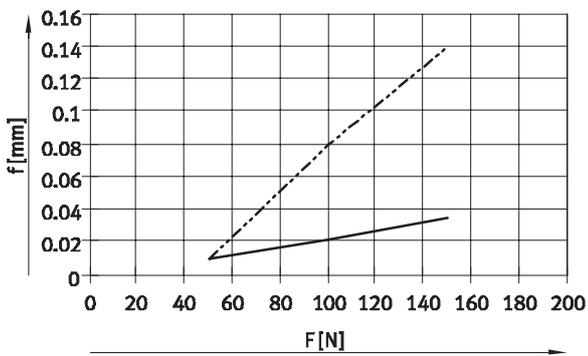
Technical data

Deflection f as a function of working stroke l and effective load F

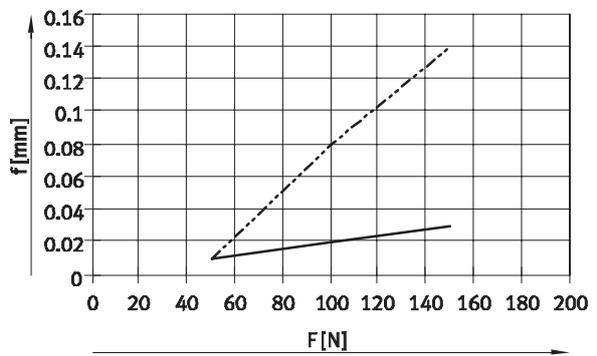


EGSA-50-100

Applied force F_y



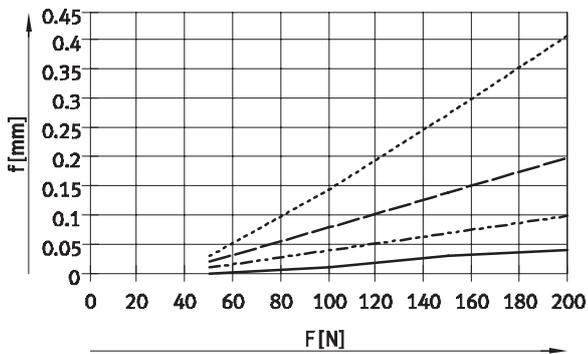
Applied force F_z



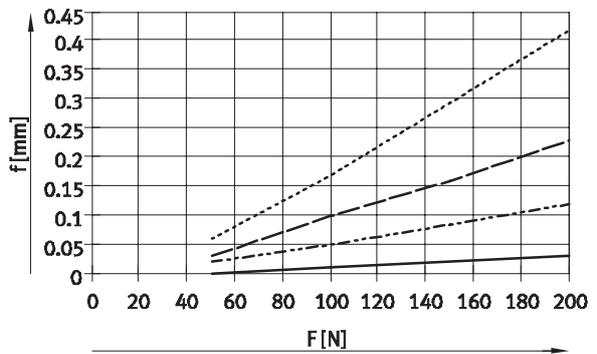
— $l = 0$ mm
 - - - $l = 100$ mm

EGSA-60-...

Applied force F_y



Applied force F_z



— $l = 0$ mm
 - - - $l = 100$ mm
 - · - $l = 200$ mm
 · · · $l = 300$ mm

Cantilever axes EGSA, with spindle drive

Technical data

Dimensions

Download CAD data → www.festo.com

EGSA-60

EGSA-50

View A

GND 5 ... 24 V DC
Signal, PNP (N/C contact)

3 Centring sleeves

1 Retracted (without stroke reserve)
2 Usable working stroke (without stroke reserve)
3 Centring sleeves included in scope of delivery
4 Lubrication facility for the spindle nut in retracted condition
5 Roller bearing for centring the attachments

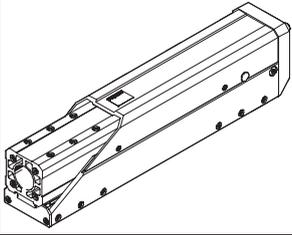
Size	Stroke [2]	Stroke reserve		B1	B2	D1 k6 ∅	D2 -0.01 ∅	D3	D4	D5 H7 ∅	D6 ∅	D7 ∅	H1	H2	H3
		Retracted	Advanced												
50	100	-3	+7	50	40	6	19	M4	M4	7	47	7 _{js7}	61.4	38	36.4
60	100	-4	+9	60	48	8	22	M5	M6	9	60	9 _{h6}	75	48	45
	200														
	300														

Size	Stroke [2]	H4	H5	L1	L2	L3* ±0.015	L4	L5	L6	L7	n1	T1 min.	T2 min.	T3 ±0.05	T4 min.	T5 min.	T6 min.	T7 ±0.1
50	100	55.4	3.6	264	100	-	15	23.5	-8	214	-	7	10	1.7	7	12	6	1.3
60	100	69	1.3	316	152	30	20	27.5	-9	258	4	10	14	2.2	12	11	15	1.8
	200			416	252					358	6							
	300			516	352					458	8							

* Tolerances for centring holes, ±0.2 for threaded holes

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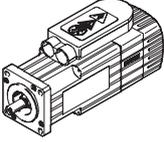
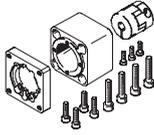
Technical data

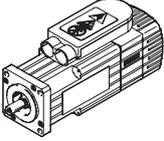
Ordering data				
	Size	Stroke	Part No.	Type
	50	100	558199	EGSA-50-100
	60	100	558200	EGSA-60-100
		200	558201	EGSA-60-200
		300	558202	EGSA-60-300

Cantilever axes EGSA, with spindle drive

Accessories

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Permissible axis/motor combinations with axial kit				
Motor	Axial kit	Axial kit consisting of:		
		Motor flange	Coupling	Coupling housing
				
Type	Part No. Type	Part No. Type	Part No. Type	Part No. Type
EGSA-50				
with servo motor				
EMMS-AS-40-...	559798 EAMM-A-A19-40A	558904 EAMF-A-28C-40A	558901 EAMC-20-30-6-6	559801 EAMK-A-A19-28C
with stepper motor				
EMMS-ST-42-...	558895 EAMM-A-A19-42A	558905 EAMF-A-28C-42A	558902 EAMC-20-30-5-6	559801 EAMK-A-A19-28C
EGSA-60				
with servo motor				
EMMS-AS-55-...	559799 EAMM-A-A22-55A	559800 EAMF-A-38C-55A	557390 EAMC-30-35-8-9	559802 EAMK-A-A22-38C
EMMS-AS-70-...	558898 EAMM-A-A22-70A	558908 EAMF-A-38C-70A	123042 EAMC-30-35-8-11	559802 EAMK-A-A22-38C
with stepper motor				
EMMS-ST-57-...	558897 EAMM-A-A22-57A	558907 EAMF-A-38C-57A	530088 EAMC-30-35-6.35-8	559802 EAMK-A-A22-38C

Permissible axis/motor combinations with parallel kit		
Motor	Parallel kit	
		
Type	Part No.	Type
EGSA-50		
with servo motor		
EMMS-AS-40-...	559785	EAMM-U-A19-40A
EGSA-60		
with servo motor		
EMMS-AS-55-...	559786	EAMM-U-A22-55A
EMMS-AS-70-...	559787	EAMM-U-A22-70A

 Note

Technical data for motors

→ Internet: motor

Cantilever axes EGSA, with spindle drive

Accessories

Axial kit EAMM-A-...

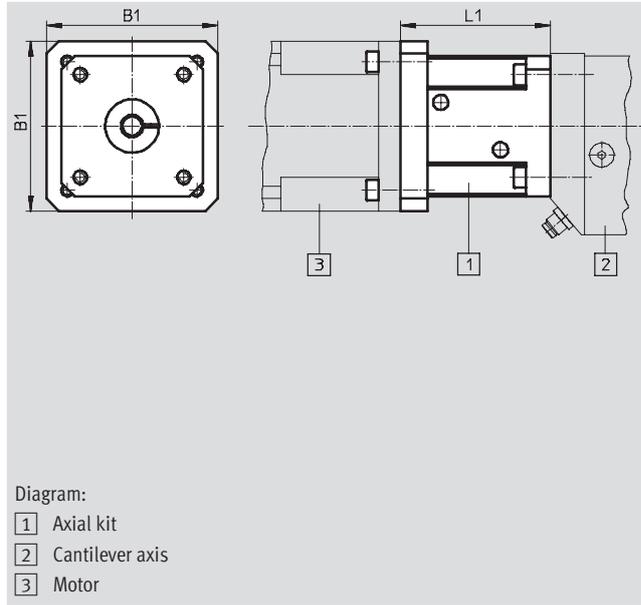
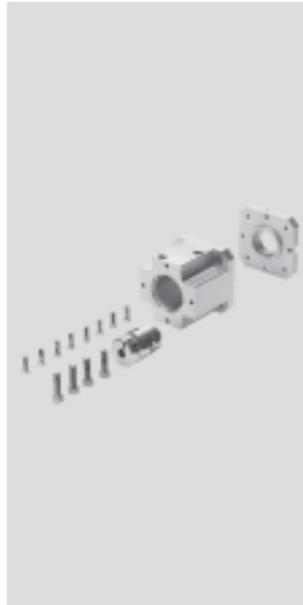
Material:

Coupling housing, motor flange:

Wrought aluminium alloy

Coupling hubs: Aluminium

Screws: Galvanised steel



General technical data						
EAMM-A-...		A19-		A22-		
		40A	42A	55A	57A	70A
Transferable torque	[Nm]	2.3	2.2	5.1	7.5	8
Mass moment of inertia	[kgmm ²]	1.06	1.06	6.06	6.06	6.06
Mounting position		Any				

Operating and environmental conditions	
Ambient temperature	[°C] 0 ... 50
Storage temperature	[°C] -25 ... +60
Protection class ¹⁾	IP40
Relative air humidity	[%] 0 ... 95
Corrosion resistance class CRC ²⁾	2
Note on material	Conforms to RoHS

1) Only with combined attachment of motor and axis

2) Corrosion resistance class 2 to Festo standard 940 070

Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Dimensions and ordering data						
Type	B1	L1	Weight [g]	Part No.	Type	
EAMM-A-A19-40A	49	49	240	559798	EAMM-A-A19-40A	
EAMM-A-A19-42A	49	55.5	270	558895	EAMM-A-A19-42A	
EAMM-A-A22-55A	58	59	430	559799	EAMM-A-A22-55A	
EAMM-A-A22-57A	58	59	430	558897	EAMM-A-A22-57A	
EAMM-A-A22-70A	70	61.5	480	558898	EAMM-A-A22-70A	

Cantilever axes EGSA, with spindle drive

Accessories

Parallel kit EAMM-U-...

Material:

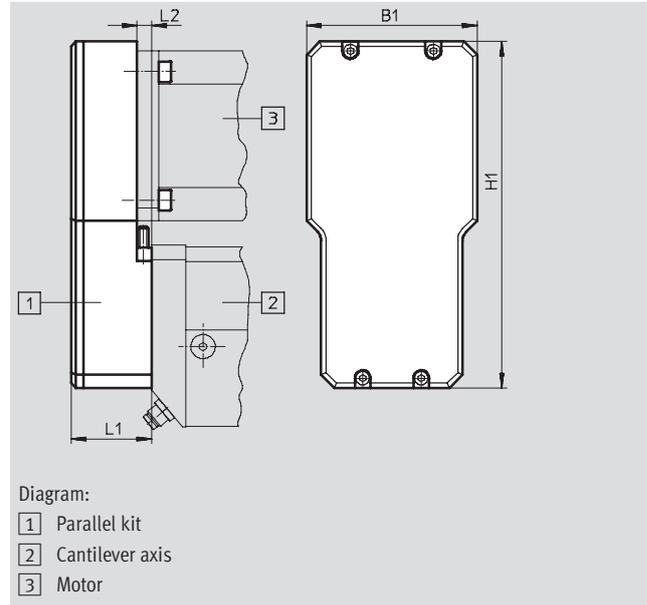
Housing, end cap, drive pulley:

Wrought aluminium alloy

Clamping sleeve: Corrosion-resistant steel

Toothed belt: Polychloroprene

Screws: Galvanised steel



General technical data				
EAMM-U-...		A19-		A22-
		40A	55A	70A
Transferable torque	[Nm]	1	3	3
No-load driving torque	[Nm]	0.05	0.1	0.2
Mass moment of inertia	[kgmm ²]	2.868	9.630	10.13
Max. rotational speed	[rpm]	6,000	4,000	4,000
Mounting position		Any		

Operating and environmental conditions		
Ambient temperature	[°C]	0 ... 50
Storage temperature	[°C]	-25 ... +60
Protection class ¹⁾		IP40
Relative air humidity	[%]	0 ... 95
Corrosion resistance class CRC ²⁾		2
Note on material		Conforms to RoHS

1) Only with combined attachment of motor and axis

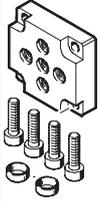
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Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Dimensions and ordering data						
Type	B1	H1	L1	L2	Weight [g]	Part No. Type
EAMM-U-A19-40A	49	107	30	7	270	559785 EAMM-U-A19-40A
EAMM-U-A22-55A	58	133	32	4.5	410	559786 EAMM-U-A22-55A
EAMM-U-A22-70A	70	143	33	6	540	559787 EAMM-U-A22-70A

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Accessories

Ordering data – Adapter kits				
	Remarks	For size	Part No.	Type
	Drive/drive connections, drive/gripper connections → Internet: hmsv	50	560017	HMSV-61
		60	560018	HMSV-62
			560019	HMSV-63

Ordering data – Connecting cables				Technical data → Internet: nebu	
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3

What must be observed when using Festo components?

Specified limit values for technical data and any specific instructions must be adhered to by the user in order to ensure recommended operating conditions.

When pneumatic components are used, the user shall ensure that they are operated using correctly prepared compressed air without aggressive media.

When Festo components are used in safety-oriented applications, the user shall ensure that all applicable

national and local safety laws and regulations, for example the machine directive, together with the relevant references to standards are observed. Unauthorised conversions or modifications to products and systems from Festo involve a safety risk and are thus not permissible.

Festo does not accept any liability for resulting damages.

You should contact Festo's advisors if one of the following apply to your application:

- The ambient conditions and conditions of use or the operating medium differ from the specified technical data.
- The product is to perform a safety function.
- A risk or safety analysis is required.
- You are unsure about the product's suitability for use in the planned application.
- You are unsure about the product's suitability for use in safety-oriented applications.

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